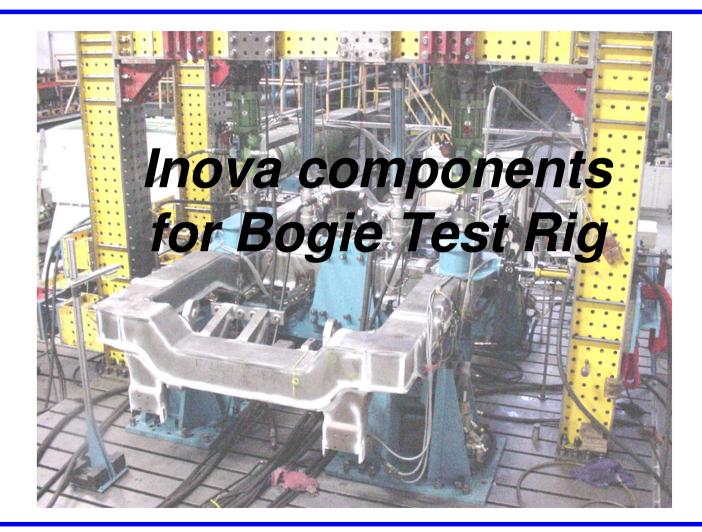
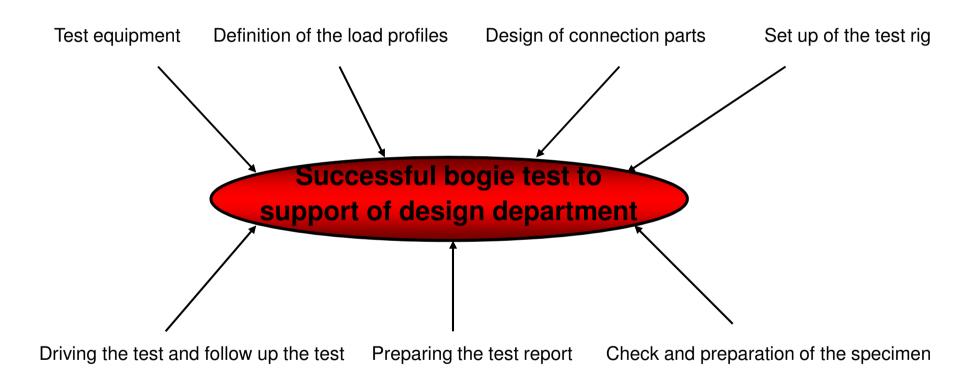


Servohydraulic Testing Systems





Target for bogie test





There are four groups of tests which have to realise:

1) exceptional loads - static

here the purpose is to proof, that the bogie frame will not permanent deformed as a result of the superposition all maxima of operational loads

2) in service loads - static

with that tests will proofed, if there are in superposition of forces (vertical, longitudinal and effects of track deformation) tiredness cracks will be expected

3) particularly operational loads - static

to proof that there are no local defects or cracks as result of repeated introduction of forces from components of the bogie (like engine, brake, damper, etc.)

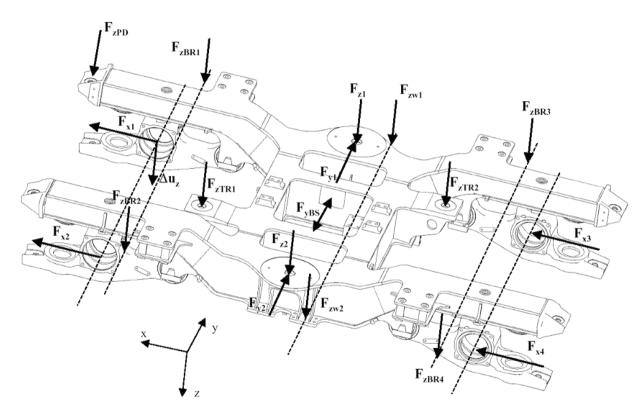
4) Fatigue tests - dynamic

Proof of fatigue strength for the bogie frame. Investigation factors of safety Looking for possible weak points, which could not found by static tests



Description of the test

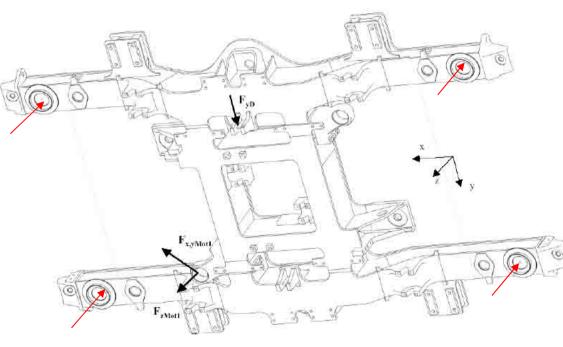
Arrangement of the forces





Description of the test

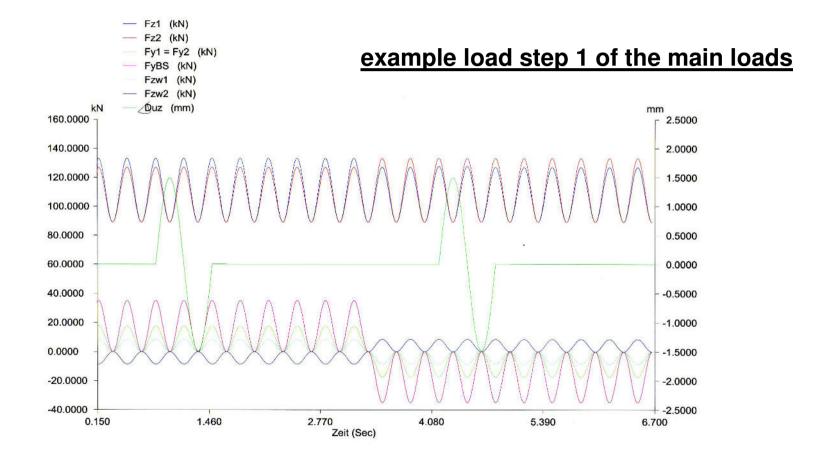
Arrangement of the forces



Rz 1..4: Reaction forces



load courses





Thyssen Transrapid at Kassel





Thyssen Transrapid at Kassel





DWA / IFS / Bombardier / RST at Berlin





DWA / IFS / Bombardier / RST at Berlin







CETEST spain





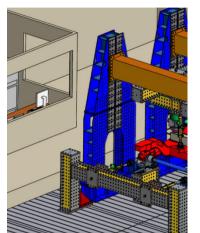
CSR Sifang Loco Qingdao

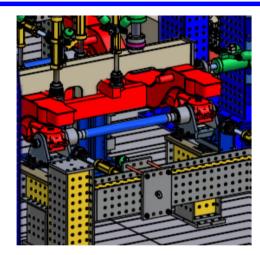


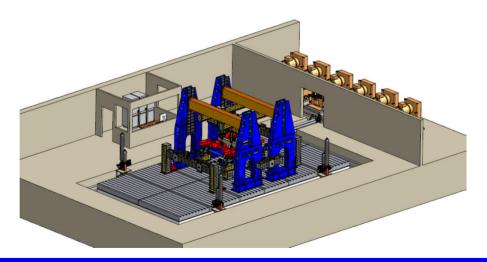




Principle of Bogie test rigs







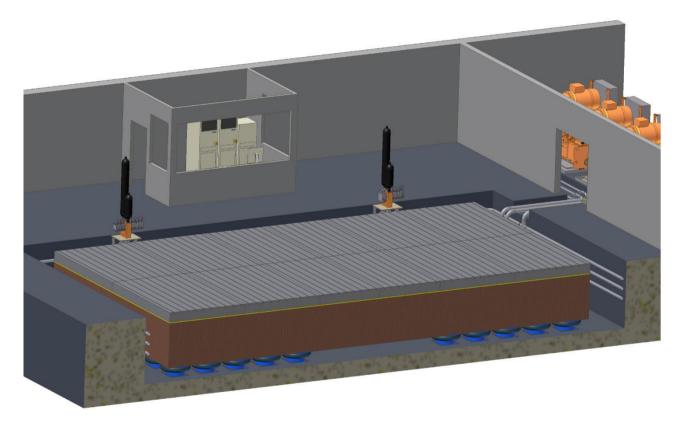
Main parts which could be done by Customer

- Civil engineer work
- Power supply
- Seismic mass
- T-slot table
- Portal frame with crossbeam
- Mounting brackets
- Attachment between bogie and rig

Main parts must be done by Inova

- Linear actuators with accessory
- Hydraulic power pack system
- Hydraulic Distribution System
- Hydraulic Control Stations
- Digital measuring an control system
- Project design and management
- Installation and training

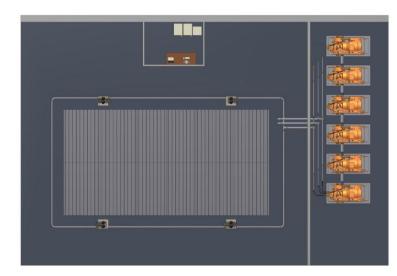




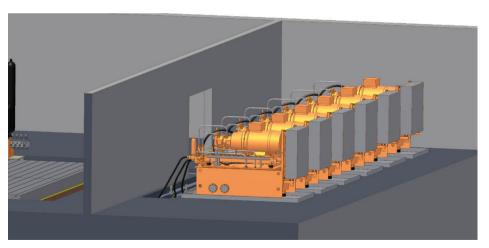
The picture shows a cross cut with a view to the air spring suspension system



Principle of Bogie test rigs



The left picture shows the top view from test area



The right picture shows the power pack station with a nominal flow of 1500 l/min



Recommended components

- First of all skilled engineers
- hydraulic actuators with high accuracy load cells
- backlash free joins
- adequate oil supply
- adequate tube system
- adequate t-slot table
- adequate Portal frame with crossbeam
- flexible Control Electronic with Test and evaluation software
- powerful data acquisition system
- Attachment between bogie and rig



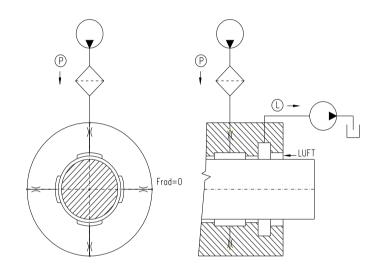
Linear actuator



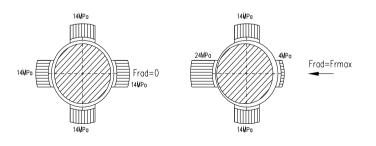
- Hydrostatic bearing linear actuators series AH
- Nom. Load from 3kN up to 2500 kN
- Nom. stroke:
 20 mm up to 400 mm



hydrostatic bearing

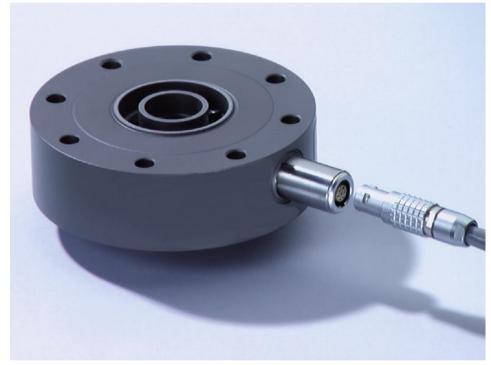


- wear and tear free
- friction free operation
- optimal control property
- high side load capacity
- suitable with permanent high speed
- maintenance free





Load cell series KA



- high accuracy class 0,1
- low influence of the side load to the measured signal (< 0.02% at Fq=0.1*Fnom)
- high stiffness
- high own frequency
- easy mounting



Ball Joints JB



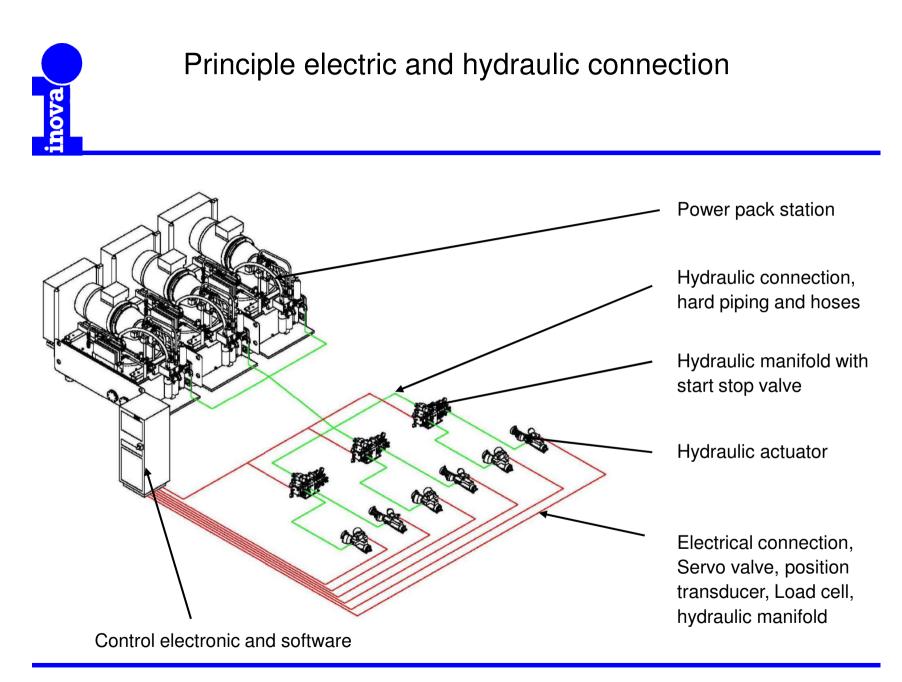
- Free from backlash, adjustable ball joints series JB
- Angle: +/- 20°
- Nom. load from 5 kN up to 630 kN
- Lowest friction
- Long service life



Cardan Joints Series JC



- free from backlash
- working angle +/- 8°
- low friction
- less maintenance work (only smear)
- long live time



Hydraulic Power Packs Series HU



- hydraulic Power Packs Series HU
- adjustable pressure (nominal pressure 280 bar)
- usage of controlled pumps
- expandable flow by connection of several power packs
- several types of power pack remote control
- long life time
- flow rate from 6.3 up to 345 l/min

Safety Start-Stop Valves Series PB



- safety Start-Stop Valves Series PB
- high pressure mode up to 315 bar
- low pressure mode 10 up to 100 bar
- restricted flow between 2l/min and 25 l/min in low pressure mode
- modular concept with flow rates of: 63, 130, 250 and 630 l/min



Digital Controller EU3000-RTC

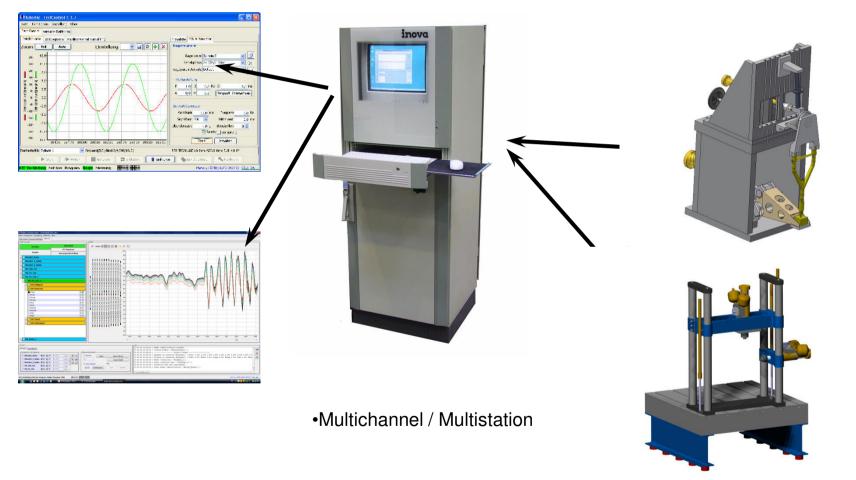




- Digital control and measure system
- Flexible configuration from one up to n.. channels
- Multi channel, multi station concept
- No limitation of number of control channels
- No limitation of numbers of amplifiers
- test frequency up to 1000 Hz
- Sample rate 10 kHz net (100 kHz brut) for each measurement channel
- Resolution 24 bit AD/DA (net)
- Loop update rate 10 kHz
- control algorithm PID, PIDF, cascade
- Control accuracy static < 0,1%, dynamic < 1%
- Phase difference accuracy
- low frequency (typical 0-5 Hz) < 3°
- middle frequency (typical 5-10 Hz) < 5°
- Digital filtration
- integrated UPS
- Pilz emergency stop system
- Big quantity of available software modules

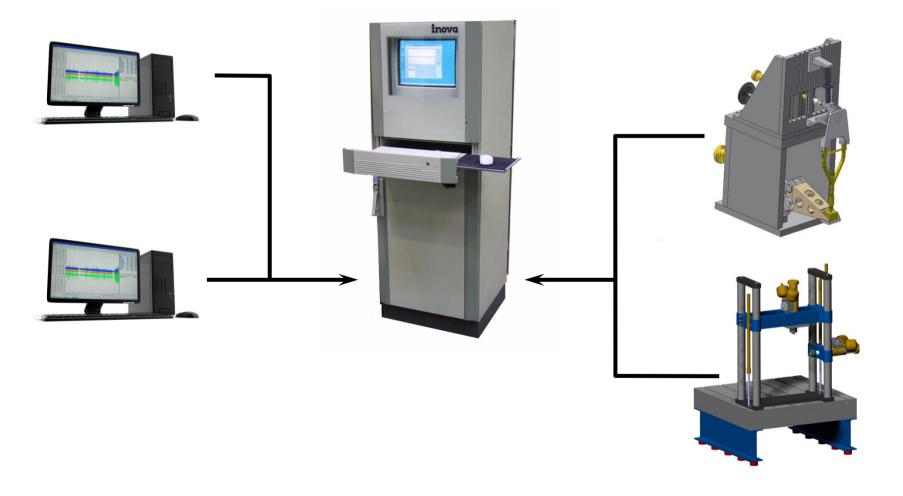


•Digital Controller EU3000-RTC



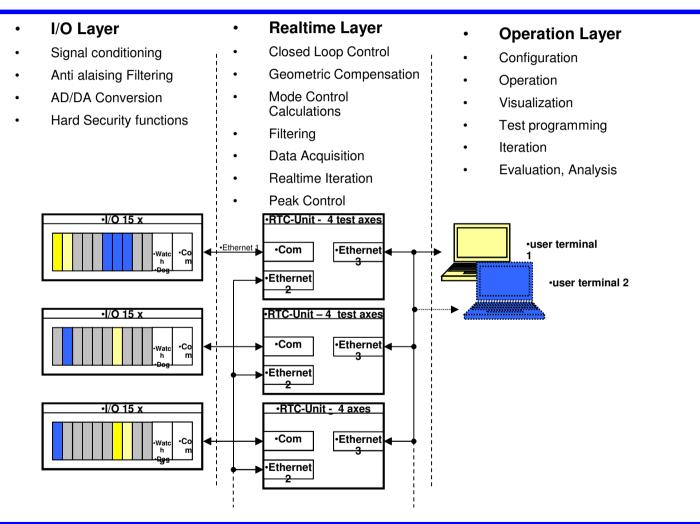


Multistation Multiuser



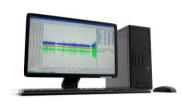


Structure EU 3000 - RTC





Scaling of EU 3000 - RTC



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		Min. stage of extension	Max. Stage of extension	Typical 12 DOF axle test rig
•Unser terminal PC	PC	1	Depends on demands	1
•RTC Real Time Controller	RTC	1	4	2
•I/O frame •with 15 slots	I/O frame	1	4*4 =16	2
 I/O moduls actuator interface (AI) signal conditioner AC/DC) analogue I/O (Ana I/A) digital I/O (Digi I/A) 	l/O Modul	2 (1 x AI + 1 x AC/DC-2)	16*15 =240	30 12 x AI 12 x AC/DC-2 2 x Digi I/A 4 x Ana I/A



available I/O cards

•

DC double amplifier, fully adjustable by software

- module provides 2 independent signal conditioner
- full bridge, halfbridge, quarterbridge DMS, potentiometric input, voltage input
- sensitivity 0,5 to 1000 mV/V
- supply voltage 2,5 to 10V
- 24 bit ADC

AC double amplifier module, fully adjustable by software

- module provides 2 independent signal conditioner
- LVDT, or half bridge input, full bridge 50 up to 5000 Ohm independent carrier frequency generators
- sensitivity 0,5 mV/V to 500 mV/V
- supply voltage 1, 2, 5 V eff max 50 mA
- phase compensation
- 24 bit ADC

AU universal double amplifier, fully adjustable by software

- module provides 2 independent signal conditioner
- full bridge, half bridge 50 up to 5000 Ohm
- sensitivity 0,5 to 1000 mV/V
- independent carrier frequency generators 1-10KHz
- excitation voltage 0,5 to 10Vef max 50 mA
- 18 bit ADC with oversampling (640kHz)
- 24 bit internal/ external resolution
- phase compensation

Analog input module

- Provides 4 independent analog inputs for general use
- free software assignment
 - general assignment as external amplifier ADC or external analog command
 - Resolution 24 bit DAC
- 10 kHz internal sampling rate, 5 kHz hardware filtering

Analog output module

- provides 8 independent analog outputs for general use or as analog outputs for amplifiers.
- free software assignment
- Resolution 16 bit DAC
- 2,5 kHz internal sampling rate
- software adjustable filters
- connection directly or via BNC input/output panel
- SV-PB module Servovalve and manifold control
- voltage to curent amplifier for servovalve exciting
- manifold and multivalve driving
- 1,2,4 servovlaves Moog G 761 or equal types
- 1,2,4 servovalves Moog 765 or equivalent (electric feedback) (Two or more valves paralell needs additional current from power supply unit)
- 1 or 2 servovalves Moog 792 or equivalent (three stage)) (Two valves paralell needs additional current from power supply unit)
- max . three solenoids 24 V DC/ 1,5A at manifold and one solenoid 24 V DC/1,5A at multiventil



available I/O cards

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Digital output module

- Module provides 16 independent digital outputs for general use ang general assignment
- free software assignment
- rating 24 V DC/1,5 A per contact
- 4 kV isolating voltage
- 2A regenerative fuses

Digital input module

- Module provides 16 independent digital inputs for general use and general assignment
- 4 kV isolating voltage
- 24 V DC support voltage from isolated supply or from internal 24 V DC

Digital input / output module

- Module provides 4 independent digital outputs
- 24 V DC (0,3A) support voltage from isolated internal supply or external 24 V DC max 1,5A (regenerative fuses 2A)
- Module provides 12 independent digital inputs
- both for general use and general assignment
- rating 24 V DC
- free software assignment
- 4 kV isolating voltage

IRC double Encoder, fully adjustable by software

- module provides 2 independent counter modules
- ABC signals, RS 422 or TTL signals
- Max. 500 kHz counting rate
- 5V or 24 V DC sensors supply
- up to 2 x 300 mA sensor supply current
- 32 bit up/down counters
- support for ultranoise transducers Balluff BTL and Stegman H Pomux

RES resolver amplifiers, fully adjustable by software

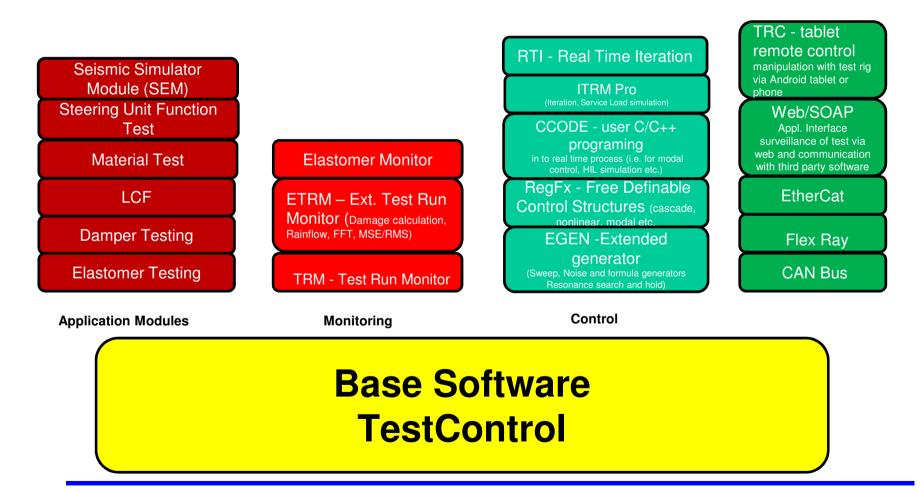
- module provides 2 independent signal conditioner
- sensitivity 3,2 V+-20% (resolver transfer 0,5-1)
- excitation voltage 1 to 20Vpp
 - independent carrier frequency generators 1-10KHz 16 bit resolution

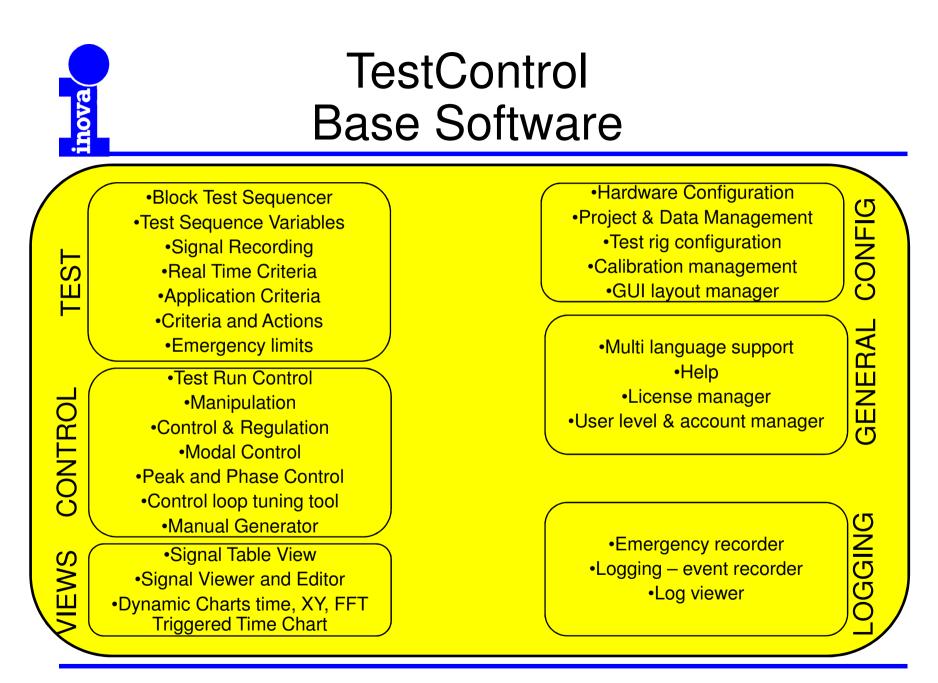
ICP double amplifier, fully adjustable by software

- module provides 2 independent ICP inputs
- isolated constant current , adjustable 1-5 mA
- adjustable gain
- high pass filter 1 Hz or 0,2 Hz
- lowpass filter 5 kHz
- integration or double integration possible in RTC



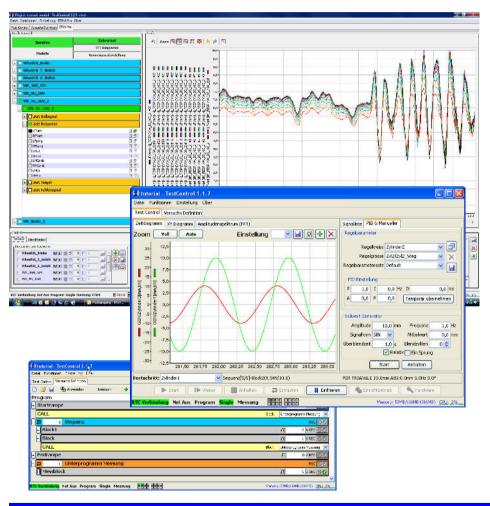
Software Modules







Software TestControl



The Software Test Control serves as the user Interface to the digital control System EU3000RTC. TestControl allows to configure the test rig, set up the loading sequence, monitors the progress of your test, handles the data acquisition and finally gives you the result of your tests. TestControl is very easy to handle. The unique user interface allows to configure test station and set up a test in minutes. The support of multi station operation allows you to run several independent tests from one PC. TestControl run on standard windows PC without special hardware requirements. TestControl itself will fulfill the most tasks in daily testing. Even replay of time histories, advanced peak control, criteria triggered test run control and comprehensive data acquisition is integrated. TestControl is extensible by plug in Modules for extended functions or special test procedures like Damper or Elastomer Testing or service load simulation with iterative transfer function compensation.



Software TestControl

	onfiguration							
N 🗋 💕	🚽 🔳 Identification 📓 🖩 🛧		Sampling frequency	10 kHz				
10	10	^	Signal settings DIGI160UT-M01					
10W-M01	8-M01 40-UT-M01 8-M01 8-M01		Signal Digital o	utput 1 💌				
11111			Name Remote	e/Enable1				
Add 🕨			NMin					
Delete	ICP2-M01 AC2-M01		NMax					
	DC2-M01		Unit					
	IRC2-M01	Defauk 1						
	DIGI16IN-M01		Comment					
	SVPB-M01 ANA8OUT-M01							
	DIGI16OUT-M01							
			Unit identification					
بل			Unit type					

Hardware Configuration

TestControl comes with a easy to use tool to set up you're the installed Hardware. All I/O cards will be shown with its name, type and at the right position in the control rack.

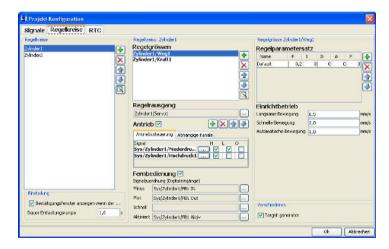
Different hardware configuration settings can be managed. A click on the Module symbol allows to change its parameters.

Si	gnale Regelkreise RTC							
4	Name	Hardware Name		ю	Туре	Unit	Min	4
1	Sys/Not Aus	DI/DIG11684-0-1-D1-1		1	BIT		0,	X
2	Sys/Zylinder1/FB1 3N	DI/DIG1684-0-1-DI-2		1	DIT		0,	1000
3	Sys/Zylinder 1/F81 Out	DUDIGI16IN-0-1-DI-3		I	BIT		0,	
4	Sys/Zyinder1/F81 Aktiv	00/0IGI160UT-0-0-00-1		0	BIT	1	0,	1
5	Sys/Zylinder1/Niederdruck1	SVP81/5VPB-0-2-DO-2		0	BIT		0,	-
6	Sys/Zylinder1/Hochdruck1	SVP81/SVP8-0-2-DO-3		0	DIT		0,	P
7	Sys/Zyinder1/LP1	DI/DIGI16IN-0-1-DI-6		[BIT		0,	
8	Sys/Zyinder2/F82 IN	DUDIGI16IN-0-1-D)-4		1	BIT	1	0,00,00,00,00,00,00,00,00,00,00,00,00,0	-
9	Sys/Zylinder2/F82 Out	DI/DIGI16IN-0-1-DI-5		I	BIT		0,	
10	Sys/Zylinder2/F82 Aktiv	00/0101160UT-0-0-00-0		0	DIT		0,	
11	Sys/Zylinder2/Niederdrudk2	SVP82/SVP8-0-3-DO-2		0	BIT		· 0,	
12	Sys/2yinder2/Hochdruck2	SVP52/SVPB-0-3-DO-3	144	0	BIT		0,	
13	Sys/ZyInder2/LP2	DI/DIG116IN-0-1-D1-7		1	BIT		0,	
14	Zylinder1/Weg1	AL1/ANA40+0-5-AJ-1		1	INT24	mm	-100	
15	Zylinder1/Kraft1	ALL/ANA4IN-0-5-AI-2	Lee.	I	INT24	kN	-100,	
16	Zyinder1/Servo1	A01/ANASOUT-0-4-A0-1	air.	0	INT16	%	-100,	
17	Zvinder2/Weg2	A11/ANA404-0-5-A1-3		1	INT24	mm	-100,	
10	Zylinder2/Kraft2	ALL/ANA404-0-5-AJ-4		1	INT24	KN.	-100,	
19	Zylinder2/Servo2	A01/ANASOUT-0-4-AO-2		0	INT16	%	-100	

Test Station Set up

TestControl comes with a easy to use tool to set up your test station.

Just choose the Hardware out of a list what is available. Use the default names or rename the signals as you want. Finally combine your in- and output signals to Control loops.



Controller Set up

In the controller set up dialog the configured inputs and outputs are combined to control loops. All signals in the system can be used to set up a controller



Software TestControl

Manual Operation

In manual operation it is easy and save to operate the test rig for specimen assembly.

To Tradicade and	Weg1	0,00 mm	т	0 mm 🕟	
Zylinder1	🔘 Kraft I	0,02 ki	6	0.00 mm	
Zylinder2	🔵 Weg2	-0,00 mm	т	0	2.stan
e zynnuerz			6	-0.00 mm	

🜒 tutorial - Tes	tControl 1.1.7							
Datei Eunktionen	Einstellung Über							
Test Control Vers	uchs Definition							
🗋 💕 🖬 🗳	Anwenden	Erneuern	4	Messung	Nachfahrsigr	nale Bedingung		
Program								REC 🔕 🥑
+ Startblock							5	0 s REC 🚫 🖉 📤
- 📮 1	Sequenz							REC 🔘 🖉
Thread1 Threa	ad2							
- Rampe1							5	0 s REC 🔕 🖉
Zylinder2	/	10	s t abs	20	mm			
- Rampe2		A A					<u>r</u>	0 s REC 🔘 🥑
Zylinder2	/	10	S TABS	0	mm			
		-96						
								~
RTC Verbindung	Not Aus Program	Single Me	ssung		1	Mem	ory: 35MB/11	6MB (381MB) <u>CPU: 296</u>

Block Programming

The unique block programmer or test sequencer is one of key elements of TestControl. It allows to set up complex, multi channel multithreaded test sequences within a graphical editor. The multithreading technology allows to set up e.g. a long term temperature profile for temperature chamber together with multiple blocks for the loading in a asynchrony overall synchronized testing sequence A delay time of 1 sample (0.1ms) between 2 blocks allows to

generate each arbitrary wave form out of ramp and sine segments.



EMERGENCY	
UNLOAD END	
JUMP	
CALL	
BREAK	
RETURN	
Set signal value	
Set signal correction	

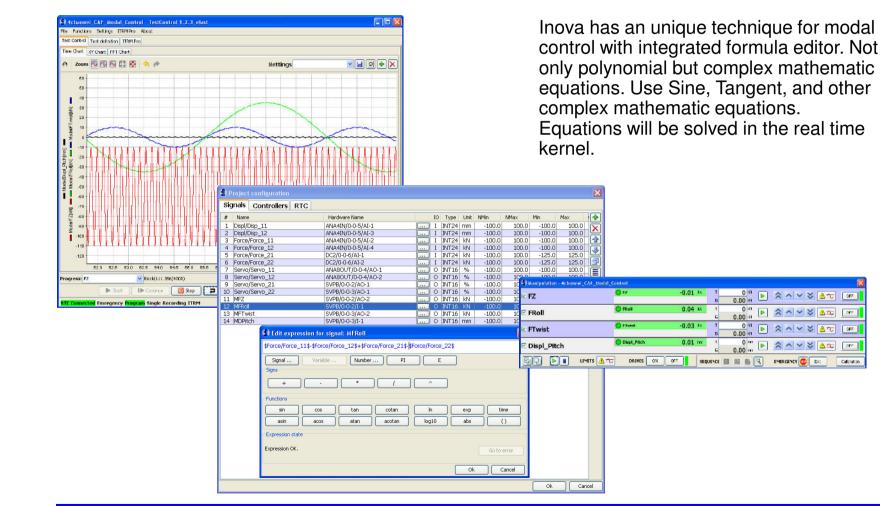
Criteria's

So called criteria's allows a event triggered run of the test with this criteria's it is possible to run a ramp in position control an stop if a defined load is reached or jump to cooling sequence if temperature of a specimen rises a certain level.

Criteria's can be combined by OR and AND function.

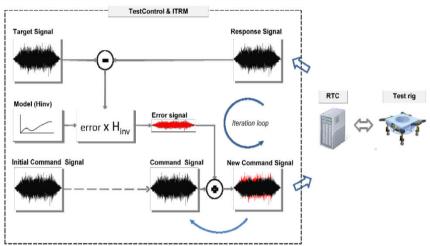


Modal control



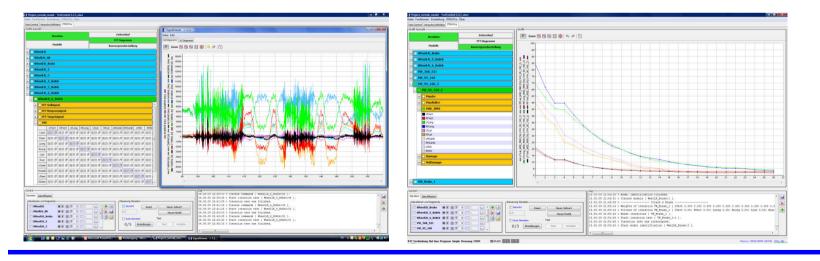


Software ITRM Pro



ITRM-Pro is the Inova frequency domain iteration Software. It is fully integrated in the TestControl package It Easy to Operate It runs fine with the

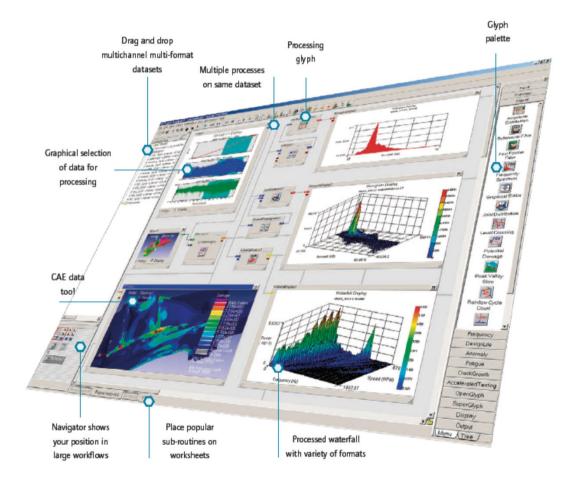
It Easy to Operate It runs fine with the default parameters. For difficult test rigs it has a lot of functions to tune the iteration process





Extended Data processing and fatigue analysis software

(third party software as ad on module)





Fatigue Analysis

(third party software as ad on module)

SN and EN Fatigue analysis

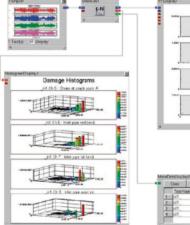
Rainflow manipulation

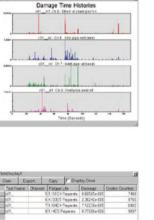
GlyphWorks provides the industry-leading technology you need to calculate fatigue-life from measured data.

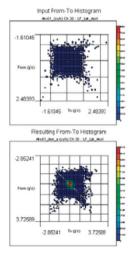
The Stress-Life (SN) method uses a nominal stress approach for high-cycle conditions or non-metallic applications; while the Strain-Life (EN) method is more appropriate for more severe loading conditions (low-cycle fatigue) – where plasticity is significant.

You can correct for mean stress and surface finish effects, even back calculate from each data channel to determine a scale or fatigue concentration factor required to achieve a target life. You could then review damage histograms to determine which load cycles were most damaging, even output damage time histories to show exactly when the damage occurred. A suite of advanced rainflow matrix manipulation and analysis tools will help you to combine, edit and extrapolate matrices.

Complete schedules of rainflow matrices to be combined into a single rainflow matrix – effectively creating the same result as driving around different sections of a proving ground. There are also statistical methods to extrapolate new matrices from existing data, either for the effect of duration (e.g. more repeats) or percentile extrapolation from given samples. The effect is more realistic than just multiplying a given matrix by a given factor, as it takes into account the likelihood of statistical variance between different runs or drivers.

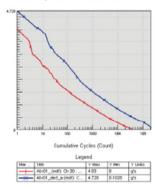








Comparison of Exceedance Plots





Technical support



Inova provides:

- Layout and design of individual test rig solution
- Design review meetings
- Manufacturing of all essential parts
- Approval and training trips to our plant
- Installation and commissioning of test equipment
- Component and system Training
- · Calibration of load and position sensors
- Technical support for customer during the test
- Maintenance









Servohydraulic Testing Systems



Inova Group South East Asia

Inova (Shanghai) Co. Ltd. Email: Ruben.siegmund@inova-world.com Homepage: inovatesting.net/